To ride a dromedary camel, you must learn how to perform stabilization. Theoretically, you must study Lyapunov Theory, local linearization, and make yourself a stabilizing feedback controller. But you may get away with self-learning by keeping getting on it, falling down from it, and re-iterate. For that, you may want to study Machine Learning. After you learn to do it, you can rigorously prove “you can do it” by applying Lyapunov Theory.

People who studied Lyapunov Theory, but could not (or did not want to) control the camel, select Bactrian camels. That is smart!